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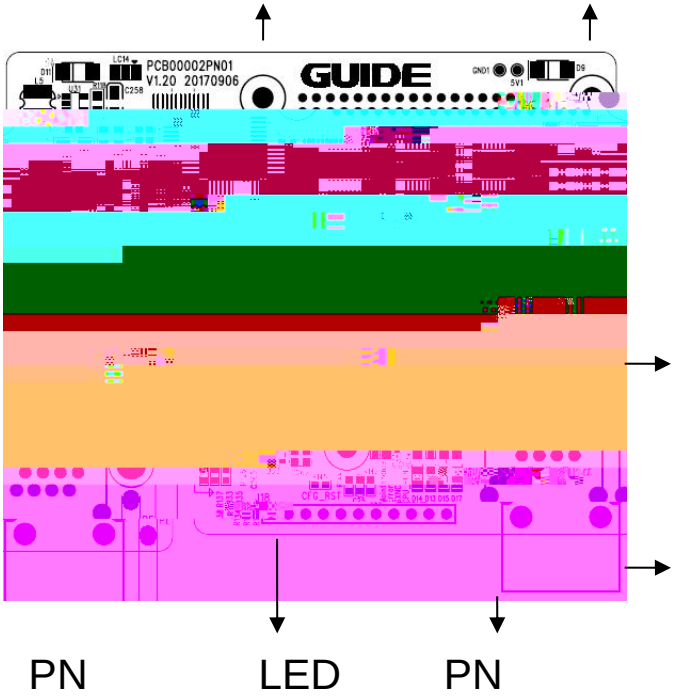

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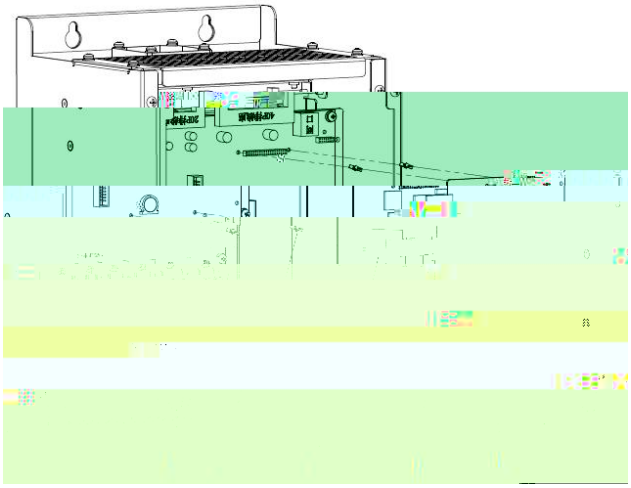

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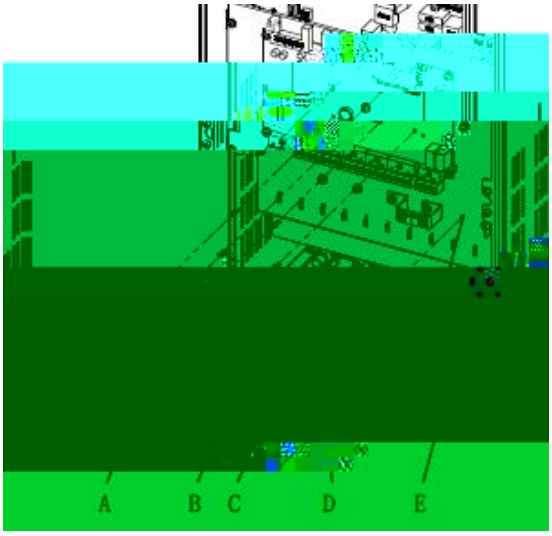

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W0	PA_CTRL ő L	0	PA_ENABLE	‘0’ Ь ą ő ḱ ‘1’ ą ő ḱ
		1	WRITE	‘0’ ‘1’ Ώ
		2	SAVE_to_FLASH	‘0’ Ь ƀ ‘1’ Ḡ ⌠ FLASH
		3 ~ 15	Reserved	
W1	Address	byte	[15..08]	[07..00]
		Data	ő	ő ˆ
W2	0	0		
W3	Data	16 β		

PA_STATUS

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CW0.11	Torque_Limit_Ctrl	└ ỵ ‘ 0 ’ ṗ ắ ‘ 1 ’ PROFINET
CW0.12 γ β	MOTION_CTRL	‘ 00 ’ 1 ‘ 01 ’ 2 ‘ 10 ’ 3 ‘ 11 ’ 4
CW0.13 β		
CW0.14	TORQUE_ZERO	w ‘ 0 ’ Ь ą ‘ 1 ’ ą w
CW0.15	FREE_RUNNING_STOP	Ả ‘ 0 ’ Ь ƀ ‘ 1 ’ Ả

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β	w	
SW0.0	READY	ΐ ح ‰ Ḥ ‘ 0 ’ ΐ ح ‰ ‘ 1 ’ ΐ ح ‰
SW0.1	RUN	ΐ ح ‘ 0 ’ ΐ ح Ả ‘ 1 ’ ΐ ح ضي
SW0.2	FAULT	‘ 0 ’ ΐ ح ‘ 1 ’ ΐ ح
SW0.3	MOTOR BRAKE	Ḥ ‘ 0 ’ Ḥ ‘ 1 ’ Ḥ
SW0.4	WARNING	ᵽ Ḥ ‘ 0 ’ ΐ ح ᵽ ‘ 1 ’ ح ᵽ
SW0.5	DIRECTION	h ‘ 0 ’ h ‘ 1 ’ ΐ h
SW0.6	M_STEP0	1 ‘ 0 ’ 1 Ḥ ‘ 1 ’ 1 Ḥ
SW0.7	M_STEP1	2 ‘ 0 ’ 2 Ḥ ‘ 1 ’ 2 Ḥ

SW0.8	M_STEP2	3 ‘ 0 ’ 3 Ḥ ‘ 1 ’ 3 Ḥ
SW0.9	M_STEP3	4 ‘ 0 ’ 4 Ḥ ‘ 1 ’ 4 Ḥ
SW0.10	Reserved	
SW0.11	Reserved	
SW0.12	REMOTE/LOCAL	/ضر ‘ 0 ’ ‘ 1 ’ ضر
SW0.13	Reserved	
SW0.14 γ β	MOTION SEL	‘ 00 ’ 1 ‘ 01 ’ 2 ‘ 10 ’ 3 ‘ 11 ’ 4
SW0.15 β		

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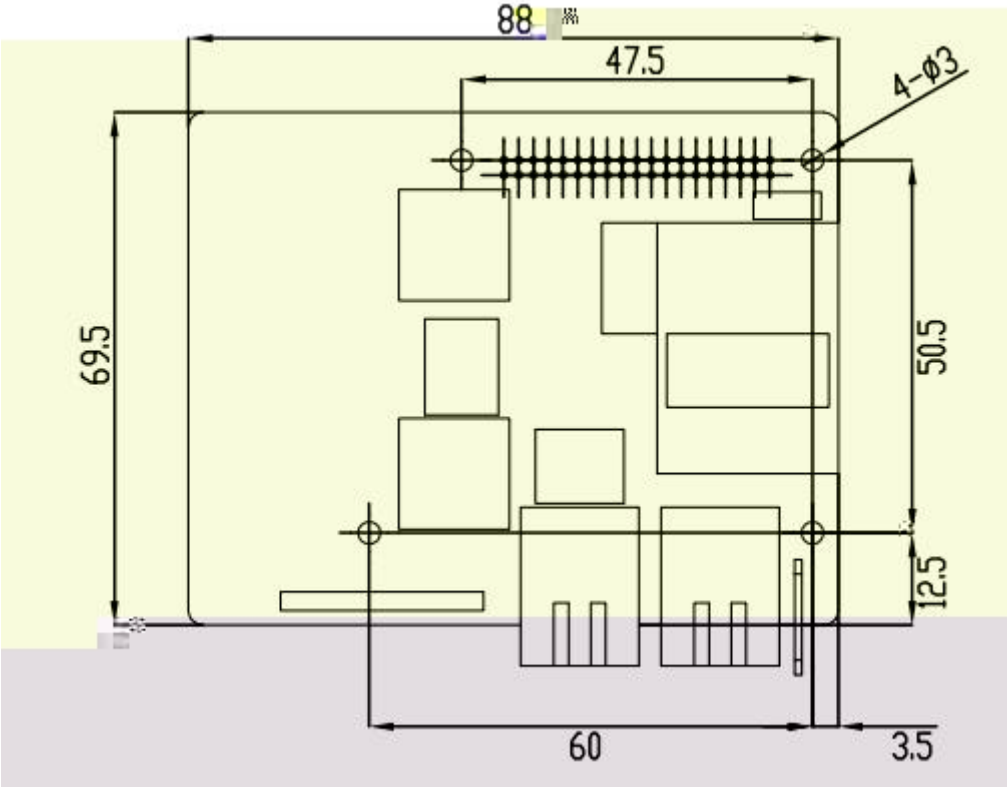

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	<110	--	Ω/km
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r	>0.34	>0.22	mm^2

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